## **Lecture 9**

## **Quadratic form**

Any homogeneous polynomial of degree 2 in 'n' variable is called quadratic form.

 $f(x_1, x_2, x_3) =$ 

is called system of linear equations which can be represented in the matrix form as AX = c where,  $A : \mathbb{R}^n \longrightarrow \mathbb{R}^n$  such that  $(x_1, x_2, x_3)$  maps to  $(c_1, c_2, c_3)$ .

Thus if  $X\in \mathbb{R}^2$ ,  $X=egin{bmatrix} x_1 \ x_2 \end{bmatrix}$  then, $Q=a_1x_1^2+a_2x_2^2+a_3x_1x_2$ 

is a quadratic polynomial in 
$$x_1, x_2$$
.

if  $X \in \mathbb{R}^3$ ,

$$Q = a_{11}x_1^2 + a_{22}x_2^2 + a_{33}x_3^2 + a_{13}x_1x_3 + a_{23}x_2x_3 + a_{12}x_1x_2$$

is quadratic form in three variables.

Thus if  $X\in\mathbb{R}^n$ , $Q=a_{11}x_1^2+a_{22}x_2^2+\cdots+a_{nn}x_n^2+a_{12}x_1x_2+\cdots+a_{n1}x_nx_1+\cdots$  $\Rightarrow Q=\sum_{i=1,j=1}^na_{ij}x_ix_j$ 

is called quadratic form in n variables.

## **Classification of the quadratic form**

- 1. Positive definite quadratic form : (Q > 0  $\forall x \neq 0$ , Q = 0 iff X = 0)
- 2. Negative definite quadratic form : (Q < 0  $\forall x \neq 0$ , Q = 0 iff X = 0)
- 3. Positive semi-definite quadratic form : (Q  $\geq$  0, but there exists X  $\neq$  0 which makes Q = 0)
- 4. Negative semi-definite quadratic form : (Q  $\leq$  0, but there exists X  $\neq$  0 which makes Q = 0)
- 5. Indefinite quadratic form : ( $Q \in \mathbb{R}$ )

## **Quadratic form in matrix notation**

If  $X \in \mathbb{R}^2$ ,

Thus the quadratic form  $Q = a_{11}x^2 + a_{22}y^2 + a_{21}yx + a_{12}xy$  can be represented as  $\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$  in the matrix form.

Ex:  $Q = 2x^2 + 3y^2 + 5z^2 + 2xy + 4yz + 2zx$ 

$$\Rightarrow egin{bmatrix} x & y & z \end{bmatrix} egin{bmatrix} 2 & 2 & 0 \ 0 & 3 & 4 \ 2 & 0 & 5 \end{bmatrix} egin{bmatrix} x \ y \ z \end{bmatrix}$$

• We can also write the quadratic form as

$$Q = \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} x_i x_j = X^T A X$$
 $= [x_1 \quad x_2 \quad \cdots \quad x_n] egin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ dots & dots & \ddots & dots \ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} egin{bmatrix} x_1 \ x_2 \ dots \ x_n \end{bmatrix}$ 

• We always write  $Q = X^T A X$ , with A as a symmetric matrix. So,

$$Q = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j = X^T B X$$

$$=X^Tegin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \ b_{21} & b_{22} & \cdots & b_{2n} \ dots & dots & \ddots & dots \ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix} X$$

where  $b_{ij} = rac{a_{ij} + a_{ji}}{2}$  such that B becomes symmetric matrix.

Ex: If  $Q=2x^2+4y^2-8z^2-2yz+8zx-3xy$ 

$$Q = egin{bmatrix} x & y & z \end{bmatrix} egin{bmatrix} 2 & -3/2 & 4 \ -3/2 & 4 & -1 \ 4 & -1 & -8 \end{bmatrix} egin{bmatrix} x \ y \ z \end{bmatrix} = X^T A X$$

where  $A^T = A$ .

#semester-1 #mathematics #matrices