# **Lecture 3**

• If X is an eigen vector corresponding to  $\lambda$ ,  $AX = \lambda X$ , How will cX transform?

$$A(cX) = c(AX) = c(\lambda X) = \lambda(cX)$$

⇒ If X is eigenvector corresponding to  $\lambda$  then cX will also be an eigenvector corresponding to the same  $\lambda$ .

Thus eigen vector corresponding to an eigen value is **not unique**.

If let say X<sub>1</sub> is an eigen vector corresponding to λ<sub>1</sub> and X<sub>2</sub> is another eigen vector corresponding to λ<sub>2</sub>, λ<sub>1</sub> ≠ λ<sub>2</sub> ⇒ X<sub>2</sub> cannnot be eigen vector corresponding to λ<sub>1</sub>.

Proof: Suppose  $X_2$  is an eigen vector corresponding to  $\lambda_1$ .

$$\Rightarrow AX_2 = \lambda_1 X_2$$

also,

$$AX_2=\lambda_2X_2$$

 $\Rightarrow \lambda_1 X_2 = \lambda_2 X_2$ . But since  $X \neq 0$ , we get  $\lambda_1 = \lambda_2$  which is not true. Thus our assumption is wrong.  $X_2$  cannot be eigen vector corresponding to  $\lambda_1$ .

Ex: 
$$X
eq 0$$
,  $ightarrow \lambda X$  where  $A=egin{bmatrix} 1&0&0\0&2&1\2&0&3 \end{bmatrix}$  .

To get eigen values,  $|A - \lambda I| = 0$ 

$$\Rightarrow \begin{vmatrix} 1-\lambda & 0 & 0 \\ 0 & 2-\lambda & 1 \\ 2 & 0 & 3-\lambda \end{vmatrix} = 0$$

Solving the determinant we get  $\lambda=1,2,3$ When  $\lambda=1$ ,

$$(A-1 \cdot I)X = 0 \ \begin{pmatrix} 0 & 0 & 0 \ 0 & 1 & 1 \ 2 & 0 & 2 \end{pmatrix} X = 0 \ \begin{pmatrix} 0 & 0 & 0 \ 0 & 1 & 1 \ 2 & 0 & 2 \end{pmatrix} \begin{pmatrix} x_1 \ x_2 \ x_3 \end{pmatrix} = 0$$

We get the equations  $x_2 + x_3 = 0$  &  $2x_1 + 2x_3 = 0$ . Thus we get infinite eigen vectors of the form  $X = \begin{pmatrix} -k \\ -k \\ k \end{pmatrix}$ .

When  $\lambda = 2$ ,

$$(A-2\cdot I)X=0 \ \begin{pmatrix} -1 & 0 & 0 \ 0 & 0 & 1 \ 2 & 0 & 1 \end{pmatrix} X=0$$

We get the equations  $-x_1 = 0$  &  $x_3 = 0$  &  $2x_1 + x_3 = 0$ . Thus we get infinite eigen vectors of the form  $X = \begin{pmatrix} 0 \\ k \\ 0 \end{pmatrix}$ .

When  $\lambda = 3$ ,

$$(A-3\cdot I)X=0 \ egin{pmatrix} (A-3\cdot I)X=0 \ 0 & -1 & 1 \ 2 & 0 & 0 \end{pmatrix} X=0$$

We get the equations  $-2x_1 = 0$  &  $-x_2 + x_3 = 0$  &  $2x_1 = 0$ . Thus we get infinite eigen vectors of the form  $X = \begin{pmatrix} 0 \\ k \\ k \end{pmatrix}$ .

## **Properties of Eigenvalues & Eigenvectors**

- 1. If  $\lambda$  is an eigen value of A, then  $\frac{1}{\lambda}$  is an eigen value of  $A^{-1}$ .
- 2. If  $\lambda$  is an eigen value of A, then  $k\lambda$  is an eigen value of kA.
- 3. If  $\lambda_1, \lambda_2, \dots, \lambda_n$  are eigen values of A then  $\lambda_1^p, \lambda_2^p, \dots, \lambda_n^p$  will be eigen values of  $A^p$ .
- 4. If  $\lambda$  is an eigen value of A, them  $\lambda k$  will be an eigen value of A kI.
- 5. A and  $A^T$  have the same eigen value.
- 6. Product of fthe eigen values is equal to |A|.
- 7. Sum of eigen values is equal to Trace(A).

## **Proofs:**

$$egin{aligned} AX &= \lambda X \ A^{-1}(AX) &= A^{-1}(\lambda X) \ X &= \lambda(A^{-1}X) \ rac{1}{\lambda}X &= A^{-1}X \end{aligned}$$

⇒  $\frac{1}{\lambda}$  is eigenvalue for  $A^{-1}$  provided that  $A^{-1}$  exists.

corollary: If any one of eigen value of A is zero, then  $A^{-1}$  does not exist.

### property 3.

 $\begin{array}{l} \mbox{If } \lambda_1,\lambda_2,\cdots,\lambda_n \mbox{ are eigen values of A.} \\ \Rightarrow AX_i = \lambda_i X_i \ \forall \ i \in \{1, \mbox{ 2, } \dots \ , n\}. \end{array}$ 

$$A(AX_i)=A(\lambda_iX_i)=A^2X_i=\lambda_i(AX_i)=\lambda_i^2X_i$$

Therefore  $\lambda^2$  will be eigenvalues for  $A^2$ . Hence in general  $\lambda_i^p$  are eigen values for  $A^p$ .

### property 5.

$$|A-\lambda I|=0 \Rightarrow egin{pmatrix} a_{11}-\lambda & a_{12} & \cdots & a_{1n}\ a_{21} & a_{22}-\lambda & \cdots & a_{2n}\ vdots & dots & \ddots & dots\ a_{n1} & a_{n2} & \cdots & a_{nn}-\lambda \end{bmatrix}=0$$

 $|A^T - \lambda I| = 0$  will heve the same determinant hence same characteristic equation hence, same eigenvalue  $\lambda$ .

#### property 6. & 7.

$$egin{aligned} A_{2 imes 2} &= egin{pmatrix} a_{11} & a_{12} \ a_{21} & a_{22} \end{pmatrix} & \ & |A-\lambda I| &= egin{pmatrix} a_{11} & \lambda & a_{12} \ a_{21} & a_{22} - \lambda \end{pmatrix} = 0 \ & \ & (a_{11}-\lambda)(a_22-\lambda) - a_21a_12 = 0 \ & \lambda^2 - (a_{11}+a_{22})\lambda + a_{11}a_{22} - a_{21}a_{12} = 0 \end{aligned}$$

suppose  $\lambda_1, \lambda_2$  are roots of a second degree polynomial,

$$egin{aligned} & (\lambda-\lambda_1)(\lambda-\lambda_2)=0 \ & \lambda^2-(\lambda_1+\lambda_2)\lambda+\lambda_1\lambda_2=0 \end{aligned}$$

Comparing the equations, we get sum of eigenvalues = Trace(A) & product of eigenvalues = |A|.

## Linearly dependent & independent sets

If for a set  $\{v_1, v_2, \dots, v_n\}$ ,  $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0$ ,  $\alpha_i = 0 \forall i$ .  $\Rightarrow$  the set is linearly independent.

If for a set  $\{v_1, v_2, \dots, v_n\}$ ,  $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = 0$ , but for some i,  $\alpha_i \neq 0$ .  $\Rightarrow v_i$  will be linearly dependent on other vectors & the set is linearly dependent.

Ex: Identify  $\mathbb{R}^3 \rightarrow \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$  as linearly dependent or independent set.

$$egin{aligned} lpha_1(1,0,0) + lpha_2(0,1,0) + lpha_3(0,0,1) &= (0,0,0) \ &\Rightarrow (lpha_1,lpha_2,lpha_3) &= (0,0,0) \ &\Rightarrow lpha_i &= 0 orall i \end{aligned}$$

This implies  $\mathbb{R}^3$  is a linearly independent set.

#semester-1 #mathematics #matrices